

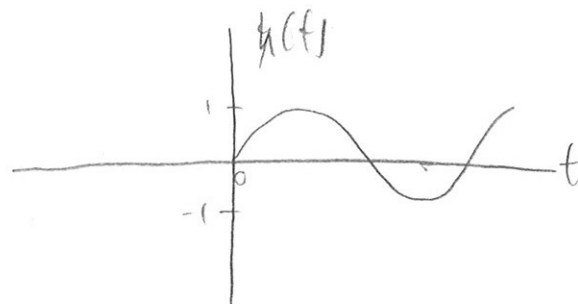
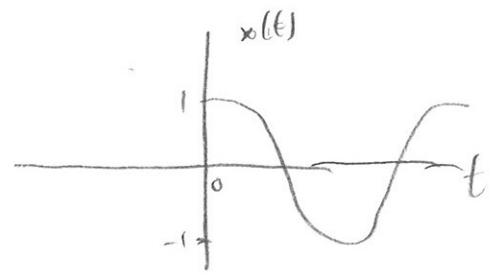
1. $x(t) = \cos(\omega t) u(t)$, $h(t) = \sin(\omega t) u(t)$

$$y(t) = (x * h)(t) = \int_{-\infty}^{\infty} x(\lambda) h(t-\lambda) d\lambda$$

$$= \int_{-\infty}^{\infty} \cos(\omega \lambda) u(\lambda) \sin(\omega(t-\lambda)) u(t-\lambda) d\lambda$$

$$= \int_0^{\infty} \cos(\omega \lambda) \sin(\omega(t-\lambda)) u(t-\lambda) d\lambda$$

$$= \int_0^t \cos(\omega \lambda) \sin(\omega(t-\lambda)) d\lambda$$

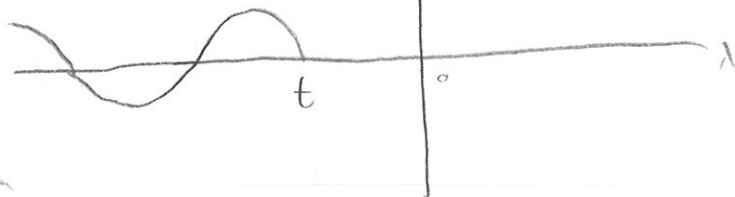
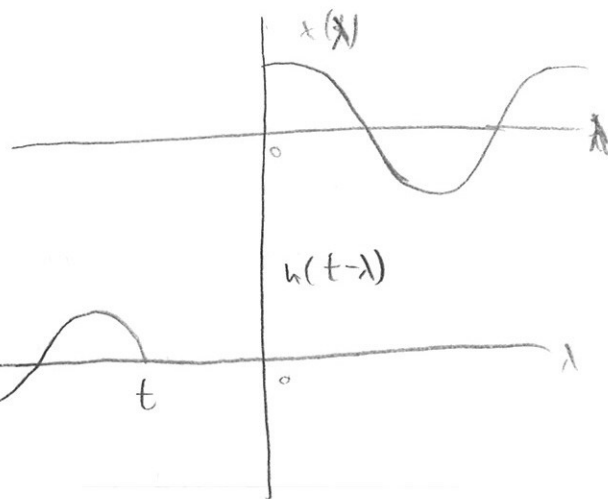


manipulate the integrand:

$$\cos(\omega \lambda) \sin(\omega(t-\lambda))$$

$$= \frac{1}{2} (\sin(\omega \lambda + \omega(t-\lambda)) - \sin(\omega \lambda - \omega(t-\lambda)))$$

$$= \frac{1}{2} (\sin(\omega t) - \sin(\omega(2\lambda - t)))$$



or if you're like me, you can't remember trig identities, but you can remember Euler's formula

$$\cos(\omega \lambda) \sin(\omega(t-\lambda)) = \frac{1}{2} (e^{j\omega \lambda} + e^{-j\omega \lambda}) \frac{1}{2j} (e^{j\omega t} e^{-j\omega \lambda} - e^{-j\omega t} e^{j\omega \lambda})$$

$$= \frac{1}{4j} (e^{j\omega t} - e^{-j\omega t} e^{2j\omega \lambda} + e^{j\omega t} e^{-2j\omega \lambda} - e^{-j\omega t})$$

$$= \frac{1}{4j} (e^{j\omega t} - e^{-j\omega t} - (e^{j\omega(2\lambda-t)} - e^{-j\omega(2\lambda-t)}))$$

$$= \frac{1}{2} \sin(\omega t) - \frac{1}{2} \sin(\omega(2\lambda-t))$$

1. cont

$$\int_0^t \frac{1}{2} \sin(\omega t) d\lambda - \int_0^t \frac{1}{2} \sin(\omega(2\lambda - t)) d\lambda$$

$$v = 2\lambda - t \\ dv = 2d\lambda$$

$$\frac{1}{2} \sin(\omega t) \int_0^t d\lambda - \int_{-t}^{2t-t} \frac{1}{4} \sin(\omega v) dv$$

$$\frac{t}{2} \sin(\omega t) - \underbrace{\int_{-t}^t}_{\text{symmetric}} \underbrace{\frac{1}{4} \sin(\omega v)}_{\text{odd}} dv = \frac{t}{2} \sin(\omega t)$$

$$y(t) = \begin{cases} 0 & t \leq 0 \\ \frac{t}{2} \sin(\omega t) & t > 0 \end{cases}$$

3

$$\begin{aligned}
 \int_{-\infty}^{\infty} (x * y)(t) dt &= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} x(\lambda) y(t-\lambda) d\lambda \right) dt \\
 &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x(\lambda) y(t-\lambda) dt d\lambda \quad (\text{by hypothesis}) \\
 &= \int_{-\infty}^{\infty} x(\lambda) \left(\int_{-\infty}^{\infty} y(t-\lambda) dt \right) d\lambda \\
 &= \int_{-\infty}^{\infty} x(\lambda) \underbrace{\left(\int_{-\infty}^{\infty} y(u) du \right)}_{\text{constant}} d\lambda \\
 &= \left(\int_{-\infty}^{\infty} y(u) du \right) \left(\int_{-\infty}^{\infty} x(\lambda) d\lambda \right)
 \end{aligned}$$

This says the area under the convolution product is the same as the product of the areas under the convolved functions. In particular, if

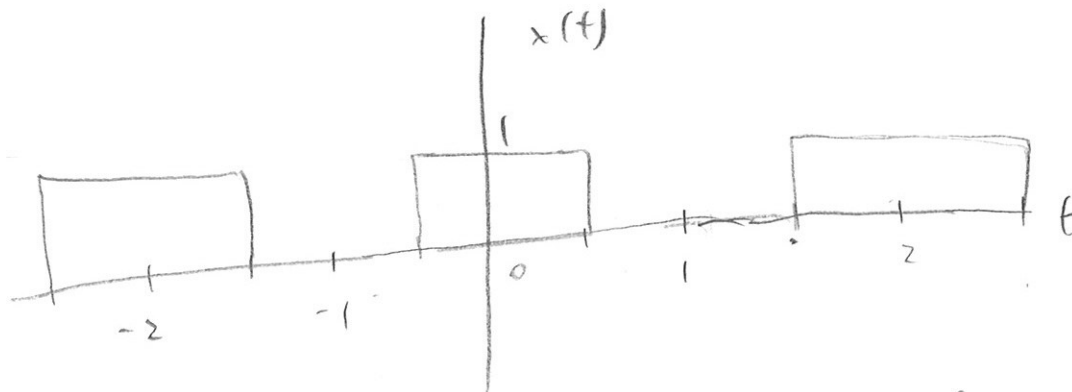
$$\int_{-\infty}^{\infty} x dt = \int_{-\infty}^{\infty} y dt = 1$$

$$\text{then } \int_{-\infty}^{\infty} (x * y) dt = 1$$

This is important because the convolution of two probability density functions is also a pdf. Convolution has a meaningful interpretation in probability theory; $(x * y)$ is the pdf of the random variable $Z = x + y$ when X has pdf $x(t)$ and Y has pdf $y(t)$ and X and Y are independent.

3.a)

$$x(t) = \Pi(t+2) + \Pi(t) + \Pi(t-2)$$



3.b)

The easy way to do this is with Fourier transforms,

$$\Pi(t) \xrightarrow{\mathcal{F}} \text{sinc}(f)$$

$$\Pi(t \pm 2) \xrightarrow{\mathcal{F}} e^{\pm 2\pi j f} \text{sinc}(f)$$

$$x(t) \xrightarrow{\mathcal{F}} X(f) = (e^{4\pi j f} + 1 + e^{-4\pi j f}) \text{sinc}(f)$$

$$Y(f) = X(f) X(f) = (e^{4\pi j f} + 1 + e^{-4\pi j f})^2 \text{sinc}^2(f)$$

$$= (e^{8\pi j f} + e^{4\pi j f} + 1 + e^{4\pi j f} + 1 + e^{-4\pi j f} + 1 + e^{-4\pi j f} + e^{-8\pi j f}) \text{sinc}^2(f)$$

$$= (e^{8\pi j f} + 2e^{4\pi j f} + 3 + 2e^{-4\pi j f} + e^{-8\pi j f}) \text{sinc}^2(f)$$

$$\text{sinc}^2(f) \xrightarrow{\mathcal{F}^{-1}} \Lambda(t)$$

$$\text{sinc}^2(f) e^{-2\pi j f t_0} \xrightarrow{\mathcal{F}^{-1}} \Lambda(t - t_0)$$

$$\Lambda(t) = (\Pi * \Pi)(t) = \begin{cases} 0 & |t| \geq 1 \\ 1 - |t| & |t| < 1 \end{cases}$$

$$Y(f) \xrightarrow{\mathcal{F}^{-1}} \boxed{\Lambda(t+4) + 2\Lambda(t+2) + 3\Lambda(t) + 2\Lambda(t-2) + \Lambda(t-4) = y(t)}$$

3.6 cont

using rules of convolution:

$$\begin{aligned}x * x &= (\pi(t+2) + \pi(t) + \pi(t-2)) * (\pi(t+2) + \pi(t) + \pi(t-2)) \\&= \pi(t+2) * \pi(t+2) + \pi(t+2) * \pi(t) + \pi(t+2) * \pi(t-2) \\&\quad + \pi(t) * \pi(t+2) + \pi(t) * \pi(t) + \pi(t) * \pi(t-2) \\&\quad + \pi(t-2) * \pi(t+2) + \pi(t-2) * \pi(t) + \pi(t-2) * \pi(t-2)\end{aligned}$$

(linearity)

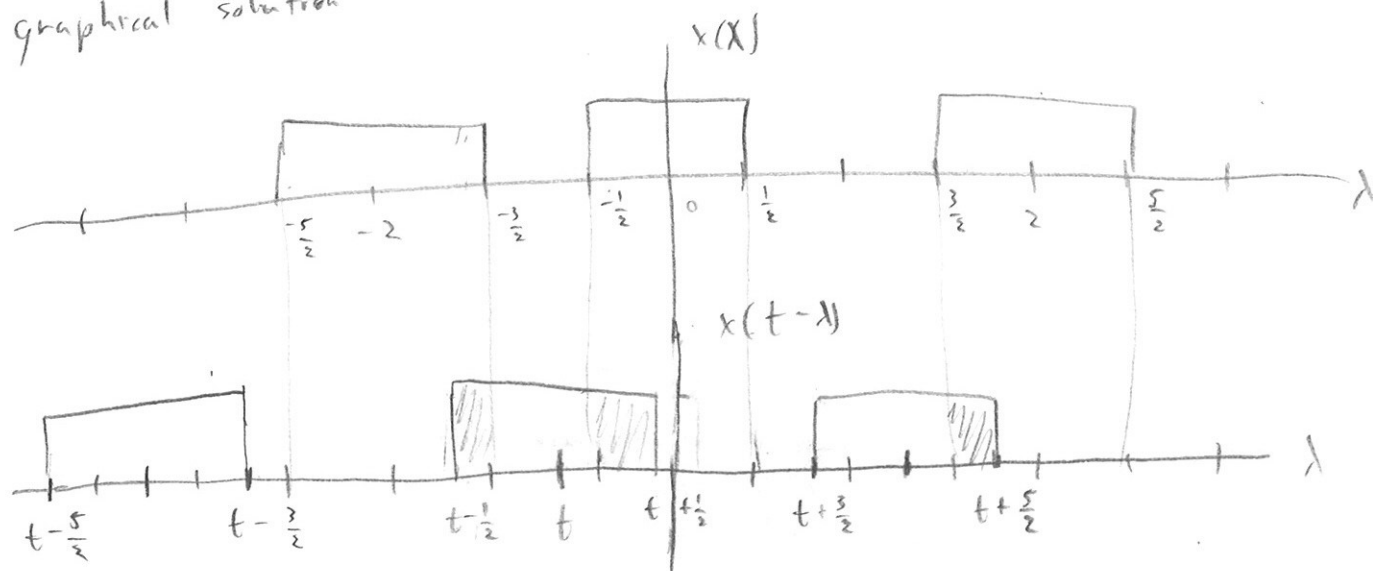
$$\begin{aligned}&= \Lambda(t+4) + \Lambda(t+2) + \Lambda(t) \\&\quad + \Lambda(t+2) + \Lambda(t) + \Lambda(t-2) \\&\quad + \Lambda(t) + \Lambda(t-2) + \Lambda(t-4)\end{aligned}$$

(translation invariance
and $\pi * \pi = \Lambda$)

$$= \boxed{\Lambda(t+4) + 2\Lambda(t+2) + 3\Lambda(t) + 2\Lambda(t-2) + \Lambda(t-4)}$$

3.6 cont)

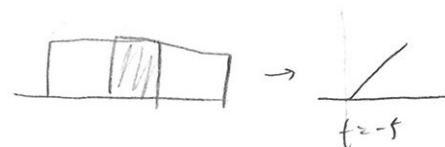
graphical solution



$$t + \frac{5}{2} < -\frac{5}{2} \rightarrow t < -5 \quad y = 0$$

$$t + \frac{5}{2} > -\frac{5}{2} \rightarrow t > -5$$

$$\text{and } t + \frac{3}{2} < -\frac{5}{2} \rightarrow \text{and } t < -4 \quad y = t - 5$$



$$t + \frac{3}{2} > -\frac{5}{2} \rightarrow -4 < t < -3 \quad y = -(t - 3)$$

$$t + \frac{3}{2} < -\frac{3}{2} \rightarrow$$

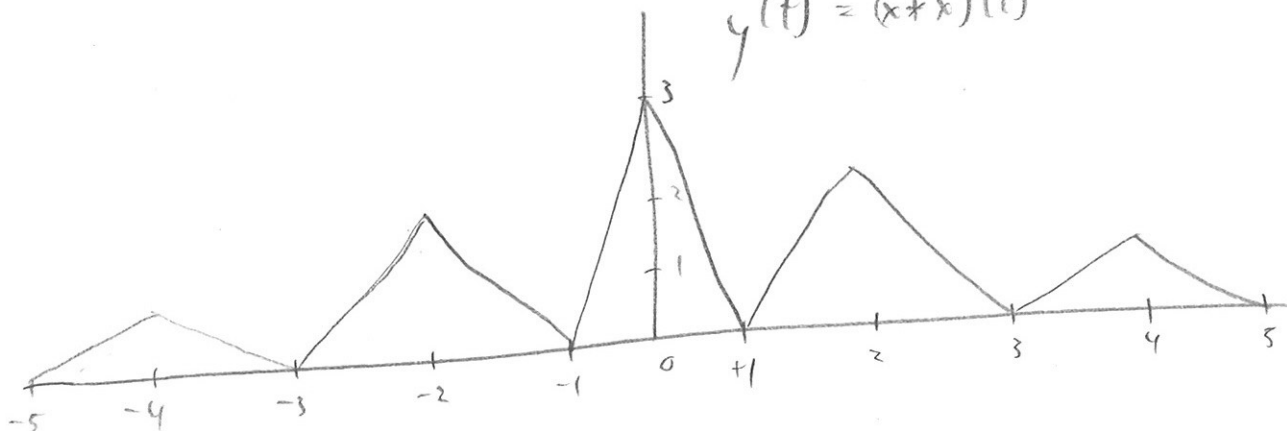


and so on...

$$y(t) = \begin{cases} 0 & t < -5 \\ t - 5 & -5 < t < -4 \\ -(t - 3) & -4 < t < -3 \\ 2(t - 3) & -3 < t < -2 \\ -2(t - 1) & -2 < t < -1 \\ 3(t - 1) & -1 < t < 0 \\ y(-t) & t > 0 \end{cases}$$

3.c

$$y(t) = (x * x)(t)$$



4.9.

$$\begin{aligned}
 x_1 * (x_2 * x_3) &= x_1 * \left(\int_{-\infty}^{\infty} x_2(t-\lambda) x_3(\lambda) d\lambda \right) \\
 &= \int_{-\infty}^{\infty} x_1(\tau) \left(\int_{-\infty}^{\infty} x_2((t-\tau)-\lambda) x_3(\lambda) d\lambda \right) d\tau \\
 &\quad \uparrow \text{const w.r.t. } \lambda \quad \underbrace{\hspace{10em}}_{g(t-\tau)} \\
 &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1(\tau) x_2(t-\tau-\lambda) x_3(\lambda) d\lambda d\tau \\
 &\quad \underbrace{\hspace{10em}}_{h(t)} \\
 (x_1 * x_2) * x_3 &= \left(\int_{-\infty}^{\infty} x_1(\tau) x_2(t-\tau) d\tau \right) * x_3(t) \\
 &= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} x_1(\tau) x_2((t-\lambda)-\tau) d\tau \right) x_3(\lambda) d\lambda \\
 &\quad \underbrace{\hspace{10em}}_{h(t-\lambda)} \quad \uparrow \text{const w.r.t. } \tau \\
 &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1(\tau) x_2(t-\lambda-\tau) x_3(\lambda) d\tau d\lambda
 \end{aligned}$$

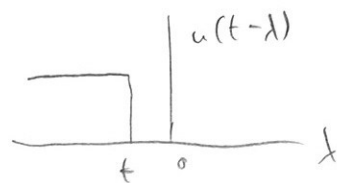
The integrand is the same in both cases, and by hypothesis we can change the order of integration, so $x_1 * (x_2 * x_3) = (x_1 * x_2) * x_3$ (convolution is associative). Fubini's theorem gives the conditions when this is a valid assumption.

4. b)

$$x_1(t) = u(t), \quad x_2(t) = \frac{d}{dt} e^{-t^2} = -2te^{-t^2}, \quad x_3(t) = u(-t)$$

$$x_1 * x_2 = \int_{-\infty}^{\infty} -2\lambda e^{-\lambda^2} u(t-\lambda) d\lambda = \int_{-\infty}^t -2\lambda e^{-\lambda^2} d\lambda$$

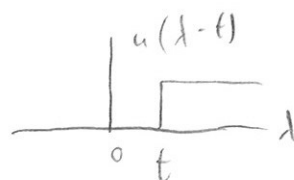
$$= e^{-\lambda^2} \Big|_{\lambda=-\infty}^t = e^{-t^2} - 0$$



$$(x_1 * x_2) * x_3 = \int_{-\infty}^{\infty} e^{-\lambda^2} u(\lambda-t) d\lambda$$

$$= \int_t^{\infty} e^{-\lambda^2} d\lambda = \frac{\sqrt{\pi}}{2} \operatorname{erfc}(t)$$

complementary error function



$$x_2 * x_3 = \int_{-\infty}^{\infty} -2\lambda e^{-\lambda^2} u(\lambda-t) d\lambda$$

$$= \int_t^{\infty} -2\lambda e^{-\lambda^2} d\lambda = e^{-\lambda^2} \Big|_{\lambda=t}^{\infty} = 0 - e^{-t^2}$$

$$x_1 * (x_2 * x_3) = \int_{-\infty}^{\infty} -e^{-\lambda^2} u(t-\lambda) d\lambda$$

$$= \int_{-\infty}^t -e^{-\lambda^2} d\lambda \quad \begin{matrix} v = -\lambda \\ dv = -d\lambda \end{matrix}$$

$$= \int_{\infty}^{-t} -e^{-v^2} -dv = -\int_{-t}^{\infty} e^{-v^2} dv = -\frac{\sqrt{\pi}}{2} \operatorname{erfc}(-t)$$

these are not equal!

$$(x_1 * x_2) * x_3 - x_1 * (x_2 * x_3) = \int_t^{\infty} e^{-\lambda^2} d\lambda - \int_{-\infty}^t -e^{-\lambda^2} d\lambda$$

$$= \int_t^{\infty} e^{-\lambda^2} d\lambda + \int_{-\infty}^t e^{-\lambda^2} d\lambda$$

$$= \int_{-\infty}^{\infty} e^{-\lambda^2} d\lambda = \sqrt{\pi} \neq 0$$

You don't need to know that $\int_{-\infty}^{\infty} e^{-\lambda^2} d\lambda = \sqrt{\pi}$, it is obviously non zero because $e^{-\lambda^2} > 0 \quad \forall \lambda \in \mathbb{R}$